Math 177. Geometric Methods in ODE Spring 2018

Take-home Final Exam

1. Prove that the following Cauchy problem:

$$(x^3 - 3xy^2)\frac{\partial u}{\partial x} + (3x^2y - y^3)\frac{\partial u}{\partial y} = 0, \ u|_{x^2 + y^2 = 2} = \sin y,$$

has no solution in a neighborhood of the point (1,1).

At the point x = 1, y = 1 the equation reads

$$-2\frac{\partial u}{\partial x} + 2\frac{\partial u}{\partial y} = 0,$$

or

$$du(v) = 0$$
, where $v = (-1, 1)$.

But the vector v is tangent to the circle $\{x^2 + y^2 = 2\}$ at the point (1,1), and hence

$$du(v) = \frac{d(\sin y)}{dy}\Big|_{y=1} = -\cos 1 \neq 0.$$

2. Consider a Lagrangian system in the upper half plane

$$\{(x,y);\ y>0\}\subset\mathbb{R}^2$$

with the Lagrangian function

$$L(x, y, \dot{x}, \dot{y}) = \frac{\dot{x}^2 + \dot{y}^2}{y^2}.$$

Write the equation of motion in the Hamiltonian form, find explicitly all the trajectories and describe qualitatively their behavior.

We have

$$H = \frac{y^2(p_x^2 + p_y^2)}{4}.$$

The corresponding Hamiltonian system is

$$\dot{x} = \frac{y^2 p_x}{2} \tag{1}$$

$$\dot{y} = \frac{y^2 p_y}{2} \tag{2}$$

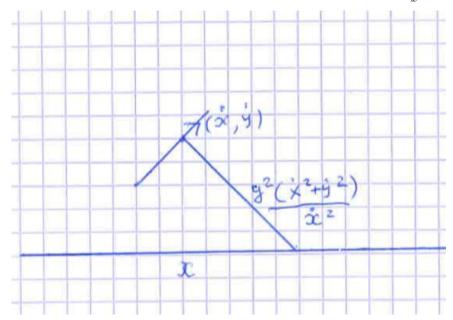
$$\dot{p}_y = -\frac{y(p_x^2 + p_y^2)}{2} \tag{3}$$

$$\dot{p}_x = 0. (4)$$

Hence we have 2 integrals, H and p_x . Recall that $p_x = \frac{\partial L}{\partial x} = \frac{2\dot{x}}{y^2}$. Hence, if $p_x \neq 0$ then

$$\frac{4H}{p_x^2} = \frac{y^2(\dot{x}^2 + \dot{y}^2)}{\dot{x}^2} = \text{const.}$$

The following picture illustrates the meaning of the quantity $\frac{y^2(\dot{x}^2+\dot{y}^2)}{\dot{x}^2}$.



Thus, $\frac{4H}{p_x^2}$ is the distance from the point (x,y) in the configuration space to the point of intersection of the x-axis with the normal to the trajectory (x(t), y(t)). In other words, all trajectories with $p_x \neq 0$ are semicircles with their center at a point of the x-axis.

If $p_x = 0$ then from the Hamiltonian system (1) we get

$$\begin{split} \dot{x} &= 0 \\ \dot{y} &= \frac{y^2 p_y}{2} \\ \dot{p}_y &= -\frac{y(p_y^2)}{2} \\ \dot{p}_x &= 0. \end{split}$$

From the integral H = E we get $p_y = \frac{2\sqrt{E}}{y}$, and hence the second equation (1) takes the form

$$\dot{y} = \sqrt{E}y.$$

Hence, x = const, $y = Ce^{\sqrt{E}t}$, and therefore the trajectory is the ray orthogonal to the x-axis.

3. Consider the contact plane field $\xi = \{dz - ydx = 0\}$ in \mathbb{R}^3 . A 1 dimensional submanifold $\Gamma \subset \mathbb{R}^3$ is called Legendrian if it is tangent to ξ . Denote by π the projection $(x,y,z) \mapsto (x,y)$. Suppose that the submanifold Γ is connected and closed (i.e. diffeomorphic to a circle). Prove that the projected curve $\pi(\Gamma) \subset \mathbb{R}^2$ must have self intersection points.

Denote the projection of the curve to the (x, y)-plane by $\overline{\Gamma}$. Note that

$$\int_{\Gamma} (dz - ydx) = 0,$$

because Γ is tangent to $\xi = \{dz - ydx = 0\}$.

But

$$\int_{\Gamma} (dz - ydx) = \int_{\Gamma} dz - \int_{\Gamma} ydx.$$

The first integral is equal to 0, because the integral of an exact 1-form over a closed curve vanishes. On the other hand,

$$\int_{\Gamma} y dx = \int_{\overline{\Gamma}} y dx.$$

But the integral in the right-hand-side is the area enclosed by the curve $\overline{\Gamma}$, and hence if $\overline{\Gamma}$ had no self-intersection points this would imply that $\int_{\overline{z}} y dx \neq 0$.